

Shared model for multi-source speech generation tasks

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1. Introduction and motivation

Many speech technologies contain speech generating stage, such as text-to-speech (TTS), voice conversion (VC), speech enhancement (SE). Recent advances in deep learning based methods significantly improve the performance of these technologies [1, 2, 3, 4, 5, 6, 7, 8].

So far, even though various successful deep learning based speech processing methods have been proposed, most of the systems can achieve only one task. For each problem, the network architecture is designed for the targeted task only and involves a long period of tuning specifically for the problem. This procedure needs to be repeated for different tasks, and this restrict the powerful effect of the neural network. The question is can we create a unified deep learning model to solve tasks cross multiple speech technologies.

We see that theoretical differences between these technologies are currently becoming much smaller than their original narrow definitions. To give a few examples, the recent advanced high-performance VC systems gain from the use of the phone posteriorgram (that is, a continuous phone representation) of inputted speech [9]. There was also an attempt to use both the spectrum features and phone posteriorgram to further improve the performance of voice conversion [4]. We can also see similar trends for TTS. The end-to-end TTS system sometimes also uses phone-embedding vectors as the input instead of letter inputs [3, 10]. There was also an attempt to use a reference audio signal as the additional input for Tacotron to transfer the prosody of the reference audio into synthetic speech via a reference encoder [11].

Given the above trends, we strongly believe that we can construct one model shared for multi-task. We assume that the speech generation related tasks can be divided into two parts: an input encoder and an acoustic decoder. The difference among the different tasks is the input. For example, the input of TTS is text characters while that of VC and SE is acoustic features. The model can be thought of as an encoder-decoder model that supports multiple encoders. The role of multiple encoder networks is the frond-end processing of each type of input data and the role of a decoder network is to predict acoustic features required for waveform generation. Our initial work starts with the joint training model for TTS&VC [12].

2. Joint training framework for TTS&VC

Inspired by the success of end-to-end TTS models, we adopt architectures similar to Tacotron for the encoders and decoder. More specifically, we have two encoders that encode different inputs and a shared decoder that predicts the acoustic features, followed by the generation of high-quality waveform signals based on WaveNet, a generative model for raw audio waveforms [13]. The other contributions of our work are as follows. First, to achieve better TTS performance with a small amount of training data, we adapt a pre-trained TTS model to a target speaker.

Second, for voice conversion, we train a many-to-one conversion to increase the size of training data while restricting the use of parallel data.

Our proposed multi-source Tacotron model is illustrated in Figure 1. It consists of a TTS input encoder, a VC input encoder, and a dual attention mechanism-based acoustic decoder followed by a WaveNet vocoder.

Both TTS input and VC input encoders have the same architecture, which includes a pre-net and a CBHG network. Each encoder transforms the corresponding input sequences into a fixed dimension state vector and a set of encoder output vectors.

The decoder of our model consists of a pre-net, an attention RNN layer, and a decoder RNN layer. Since a character embedding sequence and mel spectrogram have different time scales and we have to cope with the asynchronous input sequences, we use a dual attention mechanism. Two independent attention mechanisms Att^t and Att^v are used for transforming the outputs of the TTS and VC input encoders into context vectors, respectively.

Networks with multi-source inputs can often be dominated by one of the inputs [14]. In our proposed framework, since mapping from a source mel spectrogram to target mel spectrogram is much easier than mapping from a character embedding to a target mel spectrogram, the model will be dominated by the mel spectrogram input. To alleviate this problem, one of the following input types is randomly chosen during training: character embedding only, source mel spectrogram only, or both of the inputs to ensure that we only give specific input information to the decoder. To achieve this, we introduce a random masker for indicating which input to use during the training. Using the masker, we set the context vector that belongs to the unused input types to zero.

We jointly train the multi-source model with two inputs by using the dual attention mechanism. This mechanism allows the model to extract information from both character embedding and mel spectrogram inputs, even when one of them is absent, or the two of them are not time aligned. Given the different kinds of input to our proposed framework, we can choose which task should be achieved by setting the masker. If we use only the character embedding input, the system becomes a TTS model. If we use only the source mel spectrogram input, the system becomes a VC model. If we use both of the inputs, we can see this as a hybrid model of TTS and VC.

3. Results discussion

The results for speech quality and speaker similarity are shown in Figure 2 and Figure 3. We evaluated our model and compared it with the following systems.

- **TTS:** Stand-alone model of adapted TTS system
- **VC:** Stand-alone many-to-one VC model using same source speakers and target speaker

6. References

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